

algorithm: 5: (*6>5)+(4>3)+(2>1)

trans-
pose: 24

poly/mono: polyphonic

p.bnd range: 0

p.bnd step: 0

porta time: 0

attenuator: 0

port/gliss: portamento

porta mode: p-retain

osc sync: off

feedback: 7

op #1: on

op #2: on

op #3: on

op #4: on

op #5: on

op #6: on

op.1 level: 99

fix/ratio: ratio

base freq: 1.0

freq fine: 0

de-tune: 3

rate scale: 7

operator 1 e.g.

0	1	2	3	4	
-	96	25	25	54	
rate level	0	99	75	0	0

l curv: -lin

r curv: -lin

break point: A -1

left depth: 0

right depth: 0

a.mod sens1: 0

velo sens1: 0

op.2 level: 93

fix/ratio: ratio

base freq: 1.0

freq fine: 0

de-tune: 0

rate scale: 0

operator 2 e.g.

0	1	2	3	4	
-	17	42	35	78	
rate level	0	99	99	99	0

l curv: -lin

r curv: -lin

break point: A -1

left depth: 0

right depth: 0

a.mod sens2: 0

velo sens2: 3

op.3 level: 99

fix/ratio: ratio

base freq: 1.0

freq fine: 0

de-tune: 0

rate scale: 0

operator 3 e.g.

0	1	2	3	4	
-	96	25	25	55	
rate level	0	99	75	0	0

l curv: -lin

r curv: -lin

break point: A -1

left depth: 0

right depth: 0

a.mod sens3: 0

velo sens3: 0

op.4 level: 99

fix/ratio: ratio

base freq: 2.0

freq fine: 0

de-tune: 0

rate scale: 0

operator 4 e.g.

0	1	2	3	4	
-	95	84	20	99	
rate level	69	99	0	0	69

l curv: -lin

r curv: -lin

break point: A -1

left depth: 0

right depth: 0

a.mod sens4: 0

velo sens4: 4

op.5 level 99

fix/ratio ratio 1.0 base freq 1.0

freq fine 0 de-tune 3

operator 5 e.g.

l curv -lin r curv -lin

rate	-	96	25	25	50
level	0	99	75	0	0

break point A -1 left depth 0 right depth 0 a.mod sens5 0 velo sens5 0

op.6 level 84

fix/ratio ratio 23.0 base freq 23.0

freq fine 0 de-tune 3

operator 6 e.g.

l curv -lin r curv -lin

rate	-	79	82	20	99
level	32	88	0	0	32

break point D 3 left depth 0 right depth 0 a.mod sens6 0 velo sens6 6

lfo wave saw-up

pitch mod sens 4 lfo sync off

lfo speed 99 lfo delay 33 pitch depth 0 ampl depth 0

pitch e.g.

rate	-	94	67	95	60
level	50	50	50	50	50

wheel pitch off wheel amplitd off wheel eg bias off

wheel sens 0

foot pitch off foot amplitd off foot eg bias off

foot sens 0

aftch pitch off aftch amplitd off aftch eg bias off

aftch sens 0

brth pitch off brth amplitd on brth eg bias off

brth sens 0